# **Can Calibration Improve Sample Prioritization?**

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### **Motivation**

- Calibration can reduce overconfident predictions of deep neural networks, but can calibration also accelerate training?
- We show that performing calibration during training can -
  - Improve the quality of subsets when performing sample prioritization
  - Reduce the number of training samples per epoch (by at least 70%)
  - Speed up the overall training process
- **Pre-trained calibrated 'target' models** coupled with calibration during training can also guide sample prioritization.

# **Calibration (during training)**

A technique that *curbs overconfident predictions* in deep neural networks, wherein the predicted (softmax) probabilities reflect true probabilities of correctness (better confidence estimates).

# Experiments

- Datasets CIFAR-10, CIFAR-100 (train: validation: test 75: 10: 15)
- **Current** model => Resnet-34 (Label Smoothing, Mixup, Focal Loss)
- Target model => Resnet-50 with Mixup CIFAR-10 (α=0.3), CIFAR-100 (α=0.25)
- During sample prioritization, start with *10 warm-up epochs* with all samples selected during training (no subset selection).
  Total training epochs – *200*.
- Then, select n% of total training samples in each epoch using the Max Entropy criterion. Subset sizes used for each epoch,  $n \{10, 20, 30\}$ .
- Evaluation Metrics Expected Calibration Error (ECE) and Accuracy
- SGD Optimizer; Learning rates 0.01 (CIFAR-10) and 0.1 (CIFAR-100); Cosine annealing scheduler, Weight decay – 5e<sup>-4</sup>; Momentum – 0.9



#### **Label Smoothing**

The one-hot encoded ground truth labels  $(y_k)$  are smoothened using a parameter  $\alpha$ ,

$$y_k^{LS} = y_k(1-\alpha) + \alpha/K$$

where *K* is the number of classes. These smoothened targets  $y_k^{LS}$  and predicted outputs  $p_k$  are used to minimize the cross-entropy loss.

### Mixup

A data augmentation method which is shown to output well-calibrated predictive scores.

$$\bar{x} = \lambda x_i + (1 - \lambda) x_j$$
$$\bar{y} = \lambda y_i + (1 - \lambda) y_j$$

where  $x_i$  and  $x_j$  are two randomly sampled input data points, and  $y_i$  and  $y_j$  are their respective one-hot encoded labels.

Here,  $\lambda \sim Beta(\alpha, \alpha)$  with  $\lambda \in [0, 1]$ .

### Focal Loss

Calibrated probabilities are obtained by minimizing a regularized KL-divergence between the predicted and target distributions.

$$L_{Focal} = -(1-p)^{\gamma} logp$$

where p is the probability assigned by the model to the ground-truth correct class and  $\gamma$  is a hyperparameter.

### **Sample Prioritization**

# **Results**

Table 1: Test Accuracies (%) and ECEs (%) across various calibration techniques and subset sizes with Resnet-34 as *current* model for both datasets.

Dataset	Calibration	100%		30%		20%		10%	
		Accuracy	ECE	Accuracy	ECE	Accuracy	ECE	Accuracy	ECE
CIFAR-10	<b>No Calibration</b> Cross-Entropy (Baseline)	94.1	4.1	93.6	5.33	93.86	4.01	93.23	5.2
	Label Smoothing 0.03/0.05/0.05/0.03	94	1.84	91.74	3.17	91.48	3.56	91.72	2.71
	<b>Mixup</b> <u>0.1/0.3/0.2/0.15</u>	95.1	2.1	94.39	2.67	93.35	2.59	93.17	1.78
	<b>Focal Loss</b> <u>1/3/3/3</u>	94.69	1.71	93.19	1.2	92.6	1.25	92.25	1.42
CIFAR-100	<b>No Calibration</b> Cross-Entropy (Baseline)	77.48	5.42	73.13	10.77	71.54	13.16	69.65	14.47
	Label Smoothing 0.03/0.03/0.03/0.09	77.05	4.88	72.21	3.45	70.93	5.75	68.63	5.67
	<b>Mixup</b> 0.15/0.15/0.15/0.35	78.68	3.59	73.57	1.49	72.02	2.4	69.1	1.16
	Focal Loss <u>1/3/3/5</u>	78.59	3.57	71.86	1.67	70.61	3.25	65.81	1.82

Table 2: Test Accuracies (%) and ECEs (%) across various calibration techniques and subset sizes with Resnet-34 as *current* model for both datasets, and Resnet-50 (Mixup) as *target* model.

Dataset	Calibration	100%		30%		20%		10%	
		Accuracy	ECE	Accuracy	ECE	Accuracy	ECE	Accuracy	ECE
CIFAR-10	<b>No Calibration</b> Cross-Entropy (Baseline)	94.1	4.1	93.95	4.04	93.43	4.9	93.16	4.11
	Label Smoothing 0.03/0.05/0.05/0.03	94	1.84	93.62	2.93	93.3	3.32	93.27	1.9
	<b>Mixup</b> <u>0.1/0.3/0.15/0.15</u>	95.1	2.1	94.7	2.88	93.79	2.73	93.22	2.16
	<b>Focal Loss</b> <u>1/2/2/1</u>	94.69	1.71	93.15	1.06	92.65	1.58	92.84	1.89
CIFAR-100	<b>No Calibration</b> Cross-Entropy (Baseline)	77.48	5.42	75.38	9.36	75.04	9.39	71.07	9.27
	Label Smoothing 0.03/0.03/0.03/0.09	77.05	4.88	76.06	2.28	75.27	2.67	72.59	1.63
	<b>Mixup</b> <u>0.15/0.2/0.15/0.15</u>	78.68	3.59	75.62	0.86	74.78	1.43	70.32	0.86
	<b>Focal Loss</b> <u>1/2/3/2</u>	78.59	3.57	74.89	2.37	73.73	1.43	70.89	1.51

The process of selecting the most important samples/informative subsets during training at each epoch.

### **Max Entropy**

A de facto uncertainty sampling technique that selects the most informative (top-k) samples to maximize the predictive entropy

$$\mathbb{H}[y|x, D_{train}] := -\sum_{c} p(y = c|x, D_{train}) \log p(y = c|x, D_{train})$$

### **Pre-trained Calibrated 'Target' Models**

- Pre-trained models are used to obtain rich sample representations before training a downstream task.
- Target model a pre-trained calibrated model with larger capacity
- **Current** model model which is being trained (with/without calibration)
- Sample prioritization with a pre-trained target model at each epoch **guides** the corresponding epochs of the current model's training process.
- Note Sample prioritization with the calibrated target model is performed in addition to calibrating the current model.

- Calibration with sample prioritization => lower test ECEs across the board
- No significant trade-offs between accuracies and ECEs
- Mixup consistently performs well (high accuracies, low ECEs), Label Smoothing (least performance)
- Performing calibration during training improves sample prioritization
- Target significant improvement over current (particularly Label Smoothing)

#### References

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